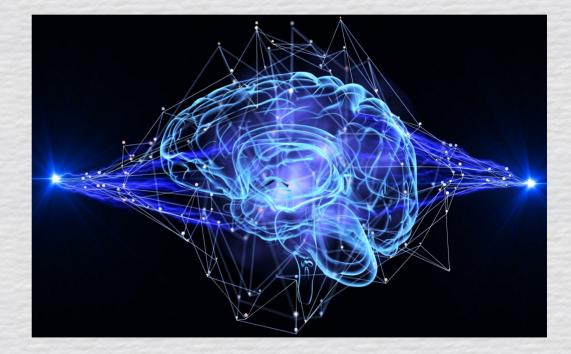


How To Build A Brain History And Core Concepts

Goals

To help you understand the history and core concepts of braininspired artificial intelligence.



AI: Not just for old white men



Marina Sarda Gou

Verena Rieser

Simi Awokoya

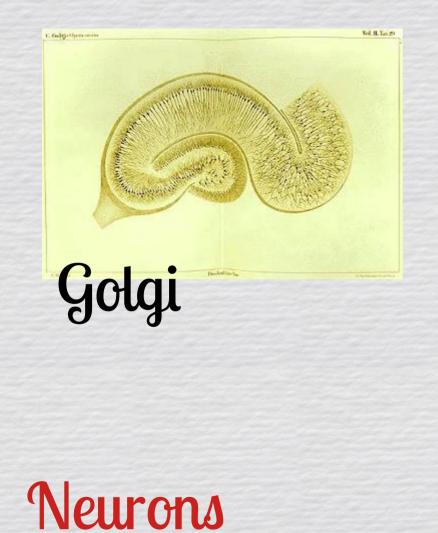


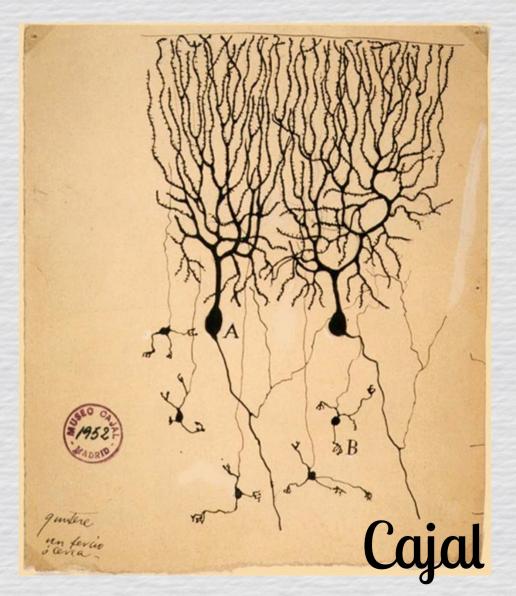
Early history



400BC - 1900AD











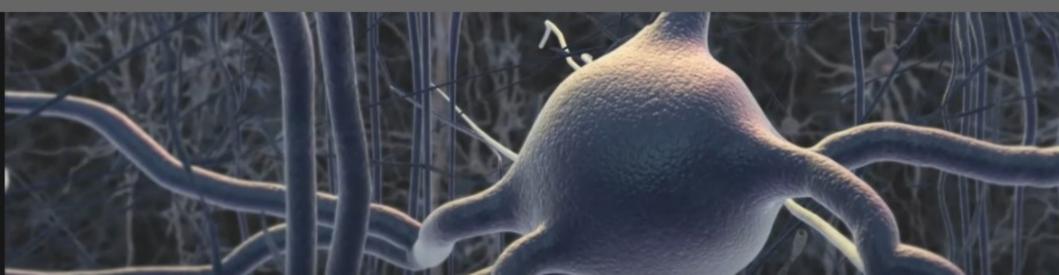


Plymouth Marine Laboratory

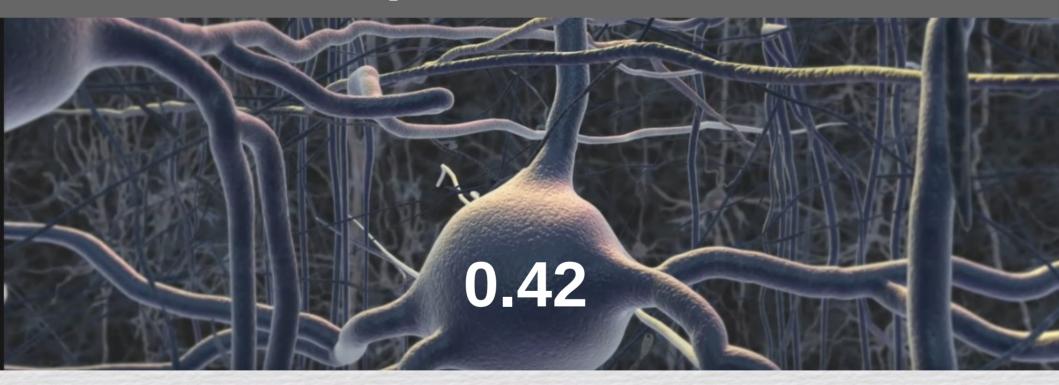
Andrew Huxley Alan Hodgkin



Three abstractions

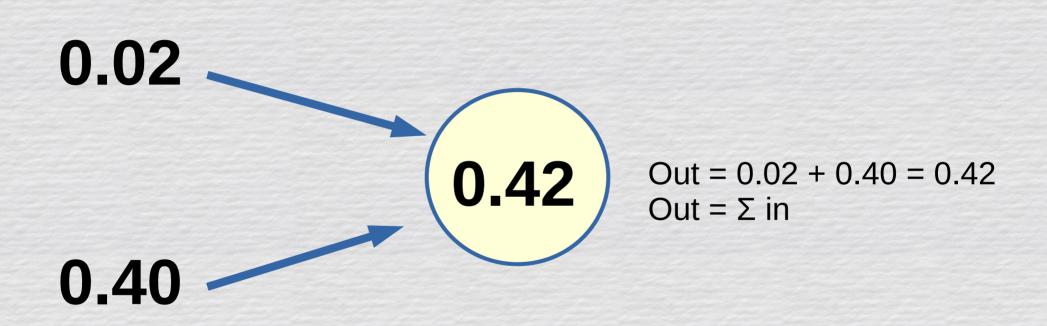


Output Activation



The activity of a neuron, as a single number

Output Activation



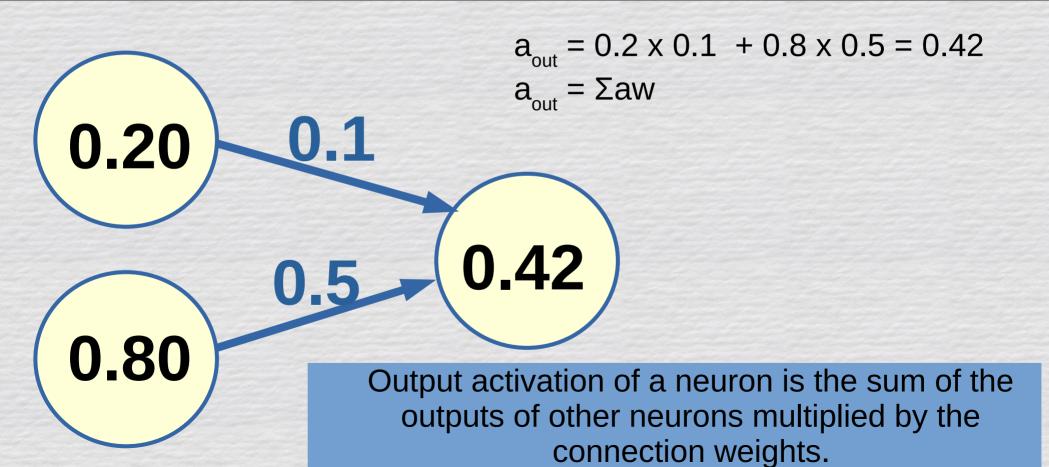
Output activation is the sum of the inputs.

Input activation

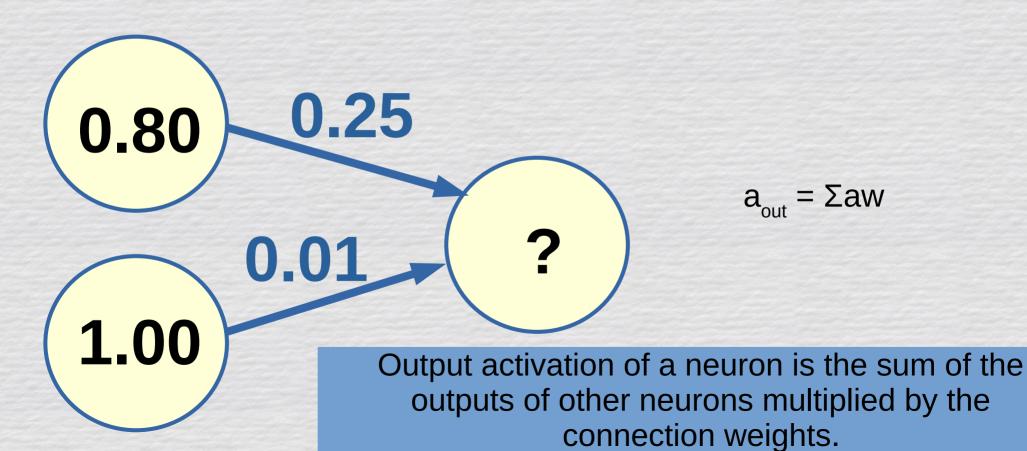


Input activation = output activation multiplied by the connection strength

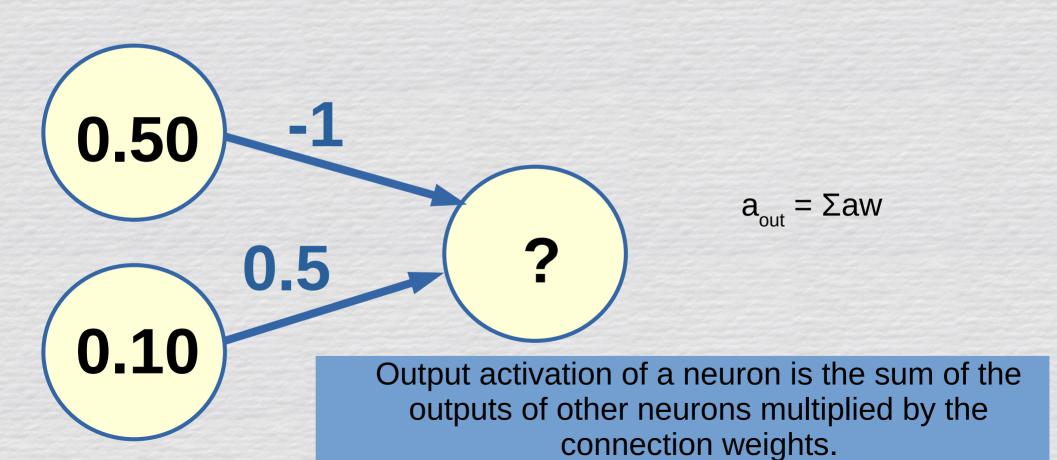
Putting it together



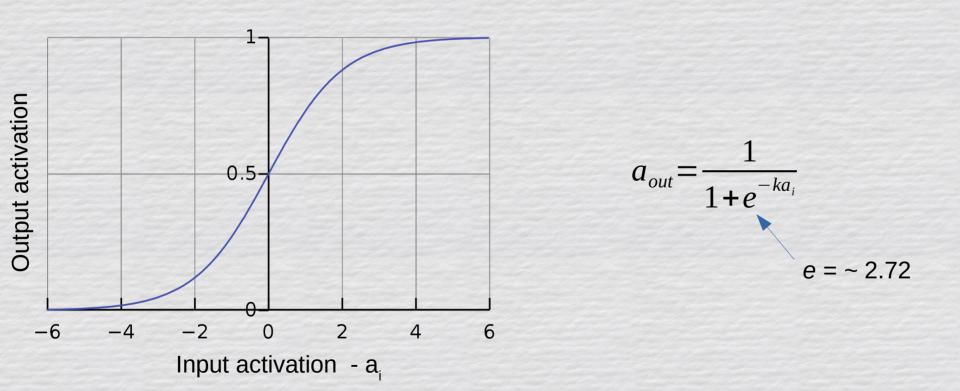
Test your understanding...



Test your understanding (2)



Activation function



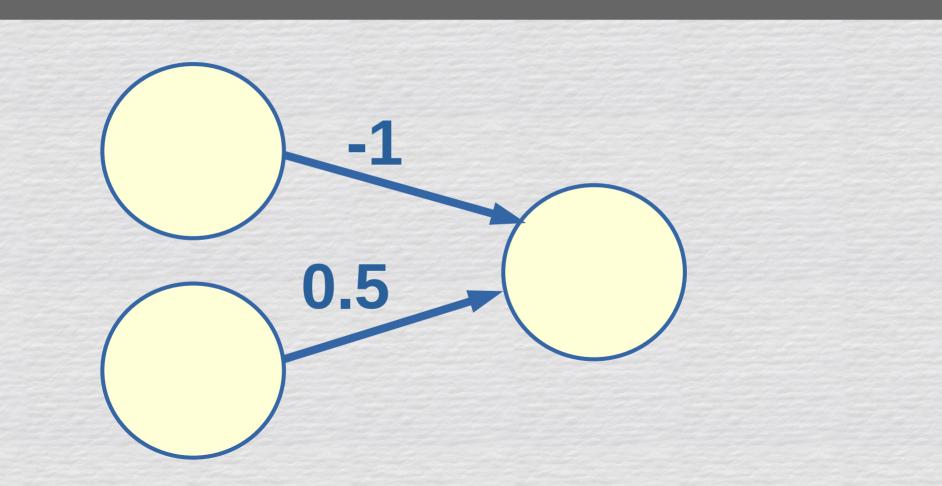
The logistic function in useful in various ways.

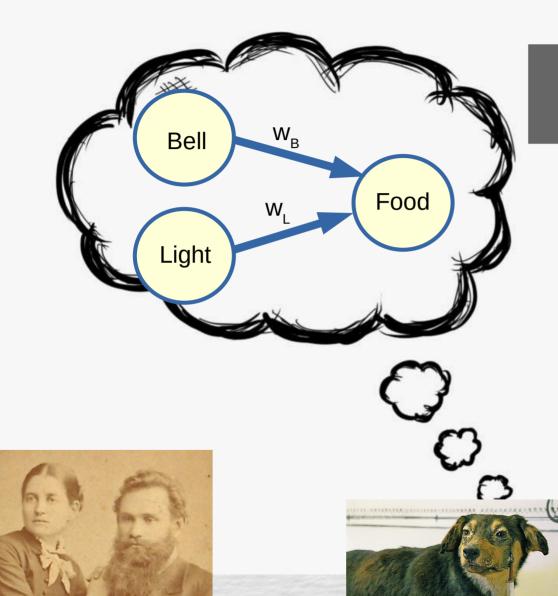


Storing knowledge



Neural Network





Neural Network

| Bell | Light | Food |
|------|-------|------|
| 1 | 0 | 1 |
| 1 | 1 | 0 |

What should W_B and W_L be?



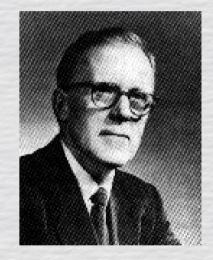
Learning



Learning



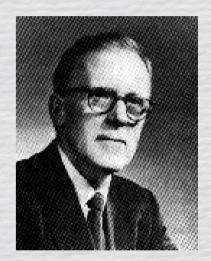




CajalKonorskiHebbSpain, 1894Russia, 1948USA, 1949

Hebbian Learning

"When an axon of cell A is near enough to excite cell B and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A's efficiency, as one of the cells firing B, is increased"

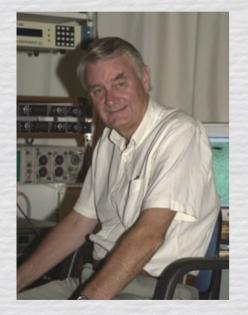


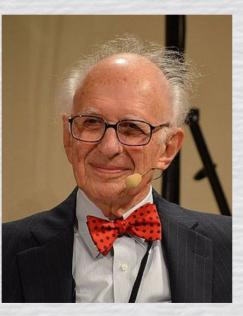
Hebb

Neurons that fire together wire together

Long-term potentiation

Neurons that fire together wire together





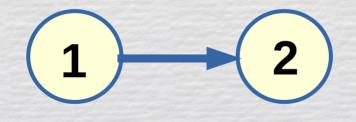
Terje Lømo

Eric Kandel

Aplysia Californica

Hebbian Learning

Neurons that fire together wire together



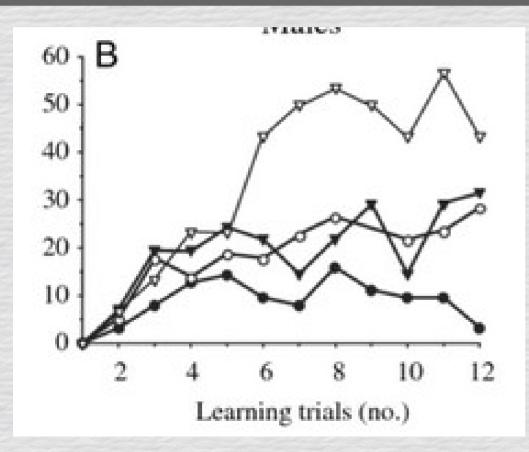
 $\Delta W_{12} = G \cdot a_1 \cdot a_2$

Hebbian Learning

| Neurons that fire together wire together | Trial | Bell | Food | Δw | W |
|--|-------|------|------|----|--------|
| | 1 | 1 | 1 | .1 | .1 |
| Bell 0 Food | 2 | 1 | 1 | .1 | .2 |
| $\Delta w = G = a$ | 3 | 1 | 1 | .1 | .3 |
| $\Delta w_{BF} = G \cdot a_B \cdot a_F$ | 1000 | 1 | 1 | .1 | 10 (!) |

G= 0.1

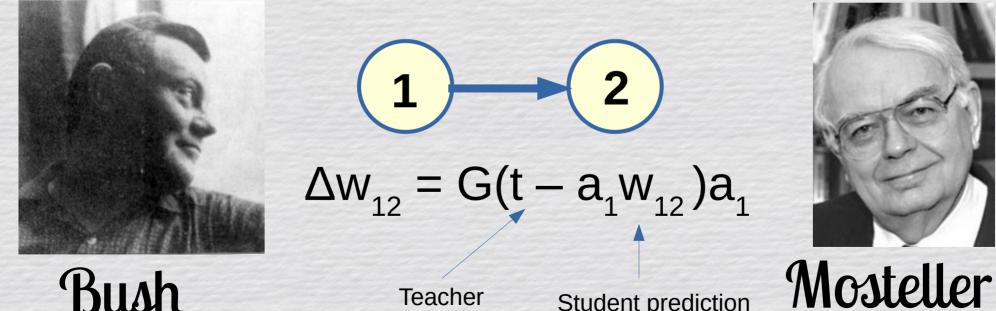
Acquisition



Learning tends to slow as it proceeds.

Bush-Mosteller

The more you know, the less you learn.



Student prediction

Bush-Mosteller

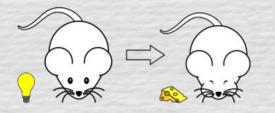
| The more you know, the less you learn. | Trial | Bell (a ₁) | Food (t) | Δw | W |
|--|-------|---------------------------|-------------|-----------------------|------|
| | 1 | 1 | 1 | .1 × (1-0×1) = .1 | .1 |
| Bell | 2 | 1 | 1 | .1 x (11x1) = .09 | .19 |
| $\Delta w_{12} = G(t - a_1 w_{12})a_1$ | | 1 | 1 | .1 × (119) = .081 | .271 |
| -11_{12} | 1000 | 1 | 1 | $.1 \times (1-1) = 0$ | 1 |

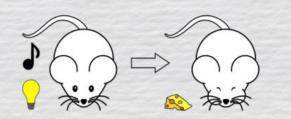


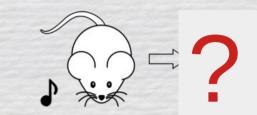
Delta rule



Blocking (Kamin, 1969)





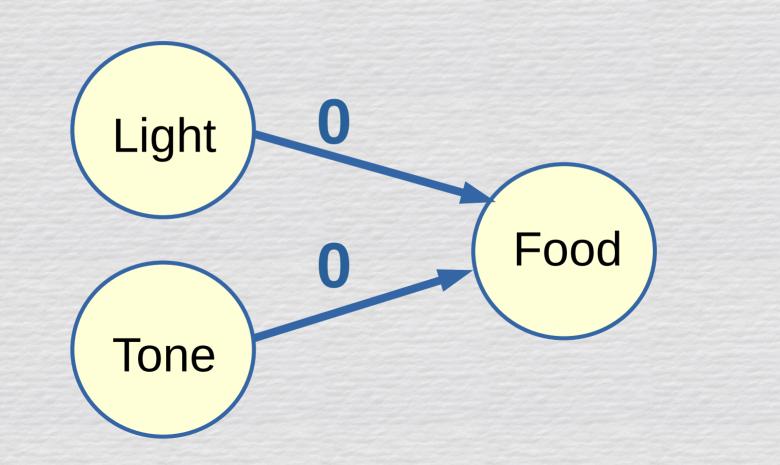




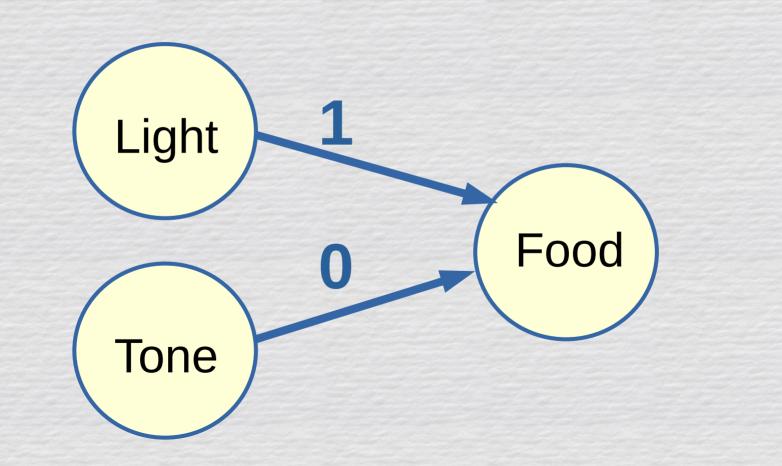
Kamin

1. Tone \rightarrow Food 2. Tone + Light \rightarrow Food 3. Light \rightarrow ?

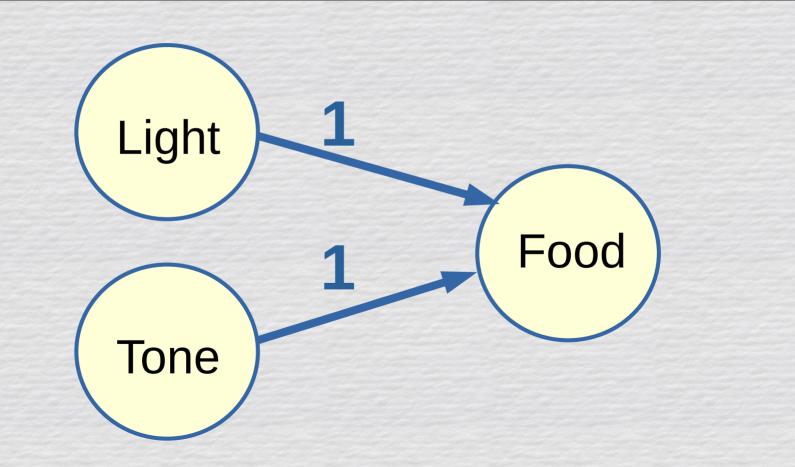
Bush-Mosteller (Blocking)



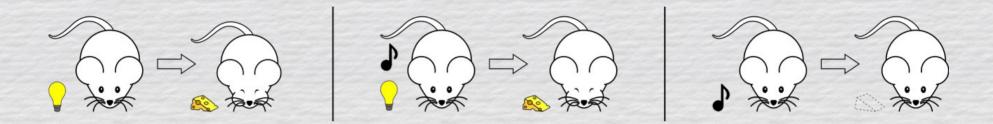
Bush-Mosteller (Blocking)



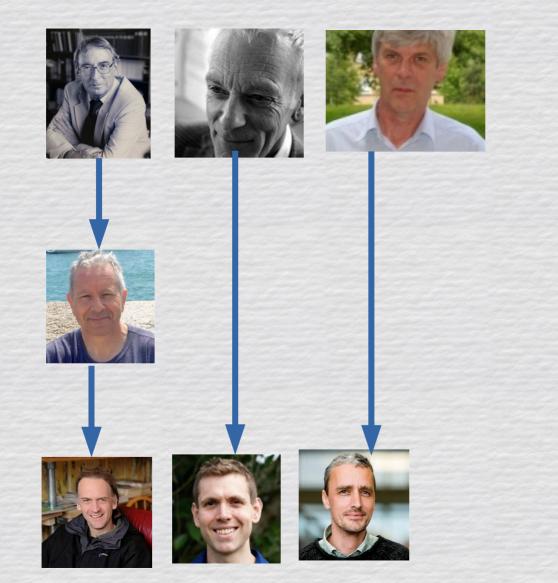
Bush-Mosteller (Blocking)



Blocking (Kamin, 1969)



1. Light \rightarrow Food 2. Tone + Light \rightarrow Food 3. Tone \rightarrow Little salivation



Why blocking?

Rescorla-Wagner (1972)

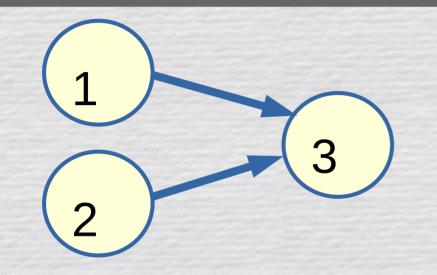


Rescorla

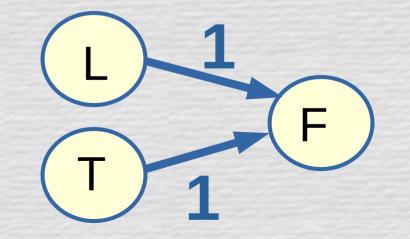




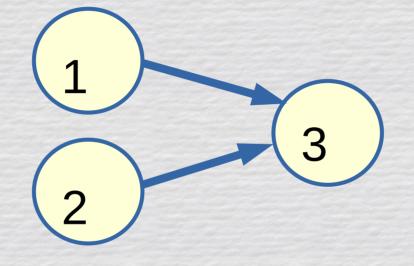
Bush-Mosteller



$\Delta W_{13} = G(t - a_1 W_{1,2})a_1$ Teacher Student prediction



Bush-Mosteller \rightarrow **Rescorla-Wagner**



 $\Delta W_{13} = G(t - a_1 W_{1,2})a_1$ $\Delta w_{13} = G(t - \Sigma a w) a_1$ Teacher Teacher Student prediction Student prediction

Stage 1: Light -> Food

| | Trial | Light (a _L) | Food (t) | ∆w _{LF} | W_{LF} |
|---|-------|----------------------------|-------------|-------------------|----------|
| (F) | 1 | 1 | 1 | .1 × (1-0) = .1 | .1 |
| 0 | 2 | 1 | 1 | .1 × (11) = .09 | .19 |
| $\Delta w = C(t - \nabla w) c$ | 3 | 1 | 1 | .1 × (119) = .081 | .271 |
| $\Delta w_{LF} = G(t - \Sigma a w) a_{L}$ | 1000 | 1 | 1 | .1 x (1-1) = 0 | 1 |

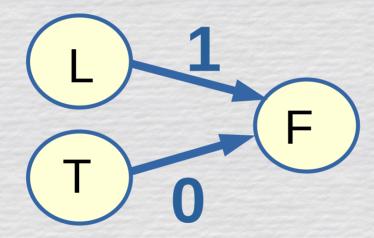
G= 0.1

Stage 2: Light + Tone \rightarrow Food

| | Trial | Tone (a _T) | Food (t) | Δw_{TF} | W _{TF} |
|---|-------|---------------------------|-------------|-----------------------|-----------------|
| (F) | 1 | 1 | 1 | .1 × (1-1) = 0 | 0 |
| 0 | 2 | 1 | 1 | .1 × (1-1) = 0 | 0 |
| $\Delta w = C(t - \nabla w) c$ | 3 | 1 | 1 | .1 × (1-1) = 0 | 0 |
| $\Delta w_{TF} = G(t - \Sigma a w) a_{T}$ | 1000 | 1 | 1 | $.1 \times (1-1) = 0$ | 0 |

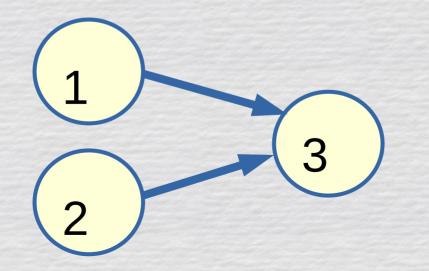
G= 0.1

Stage 3: Tone \rightarrow ?

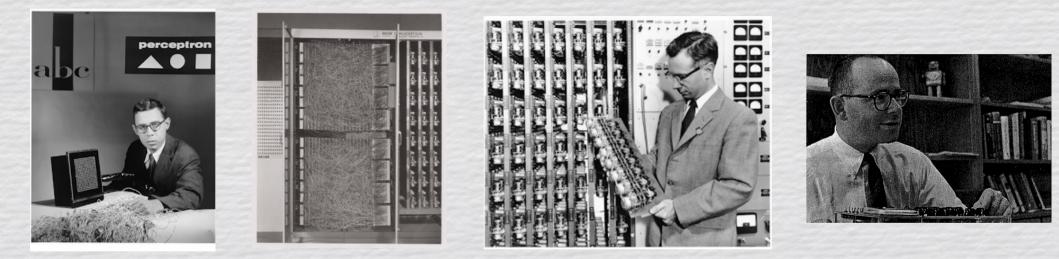


Al: Convergence rule

Mathematical proof: anything that can be learned by a single-layer network will be learned by the delta rule.



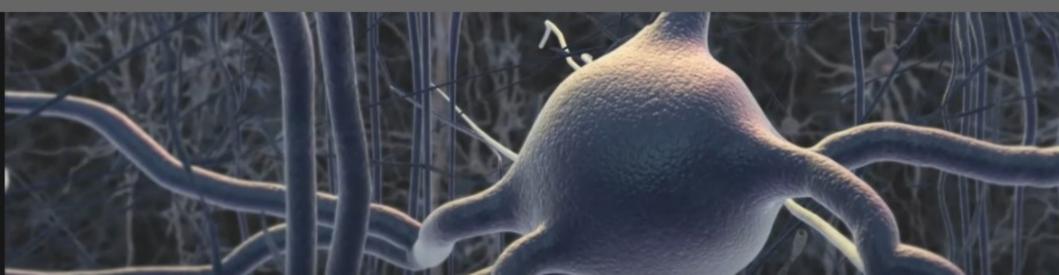
1958-1969: AI optimism



"the embryo of an electronic computer that [the Navy] expects will be able to walk, talk, see, write, reproduce itself and be conscious of its existence."



First AI Winter



XOR







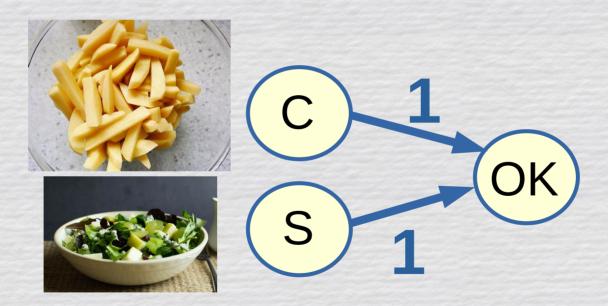
"Omelette, with chips or salad"

XOR



"Omelette, with chips or salad"

Limitations of single-layer nets



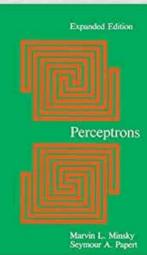
Perceptrons (1969)



Minksy



Papert



1st Al winter (1974-1980)



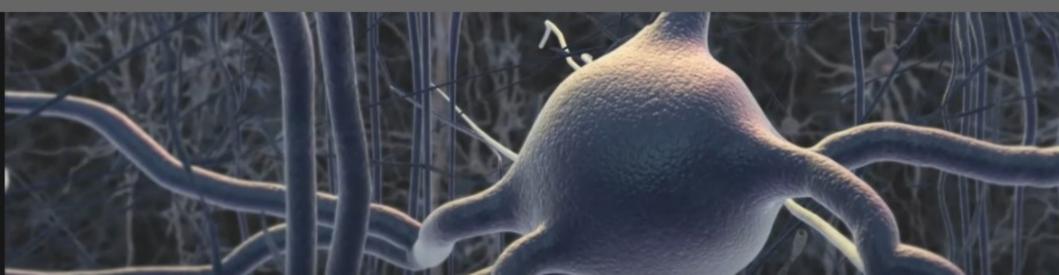
Lighthill

"In no part of the field have the discoveries made so far produced the major impact that was then promised"

- Lighthill report (1974)



Solving XOR



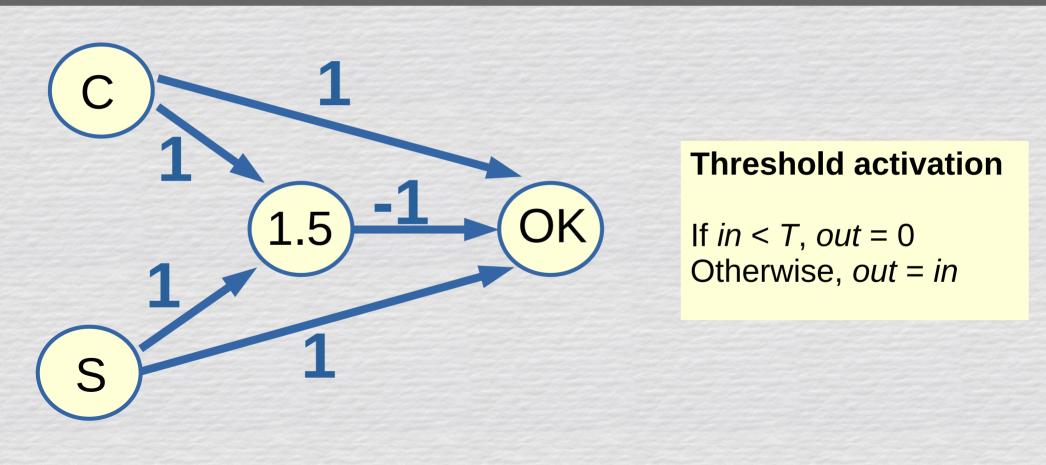
Solving XOR

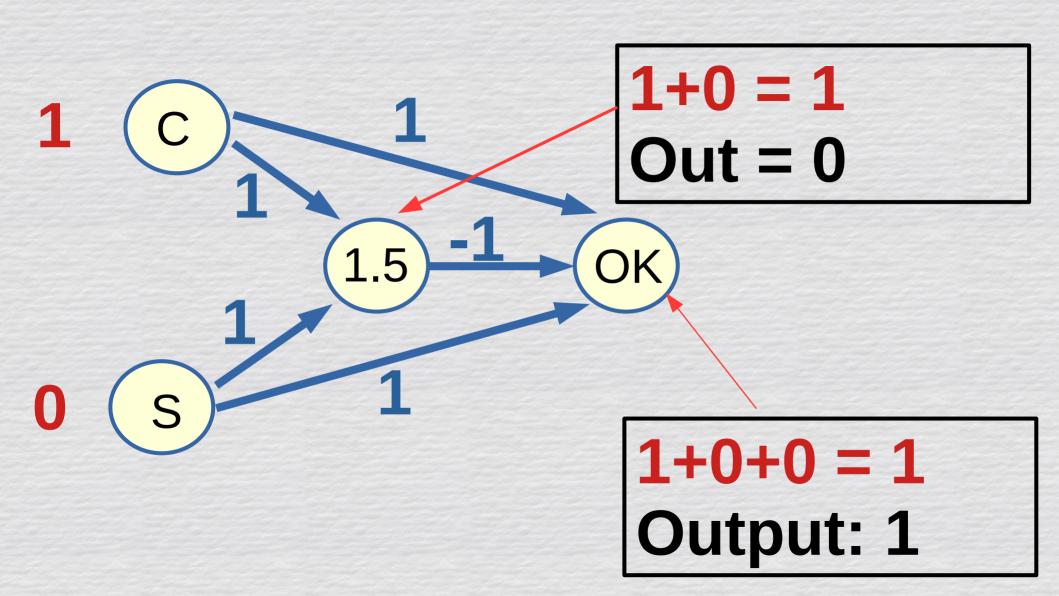
C

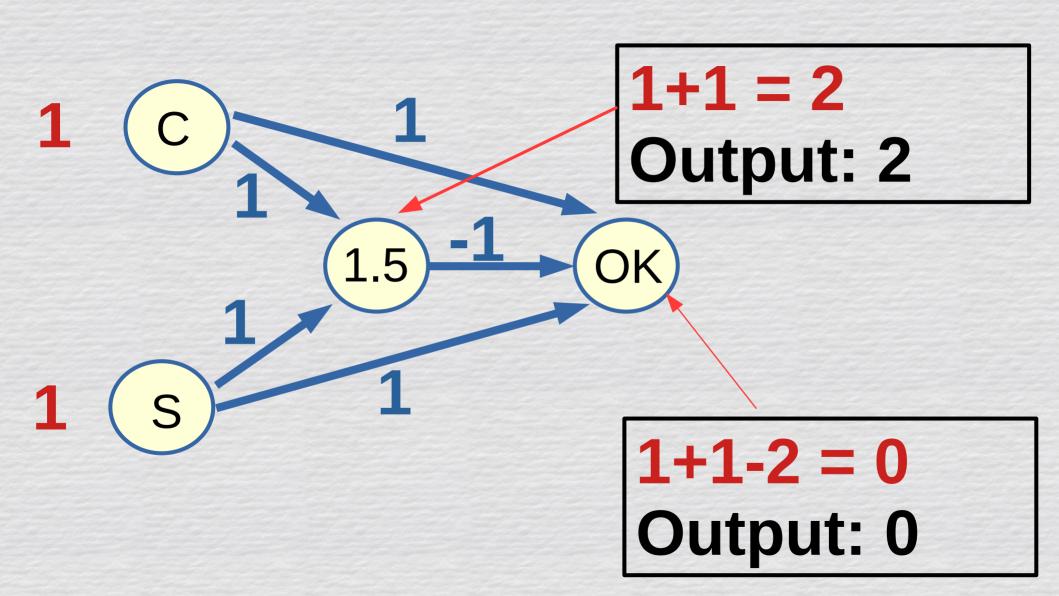
Threshold activation

If *in* < *T*, *out* = 0 Otherwise, *out* = *in*

Solving XOR









Backprop



Backpropagation of error

3

 $\Delta w_{13} = G(t - \Sigma aw)a_1$

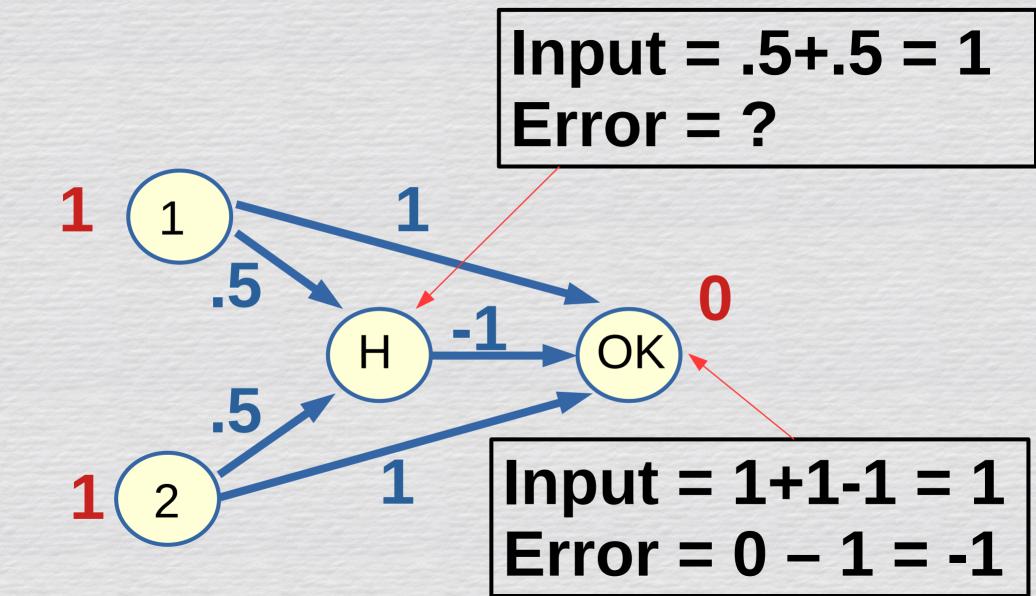
Teacher

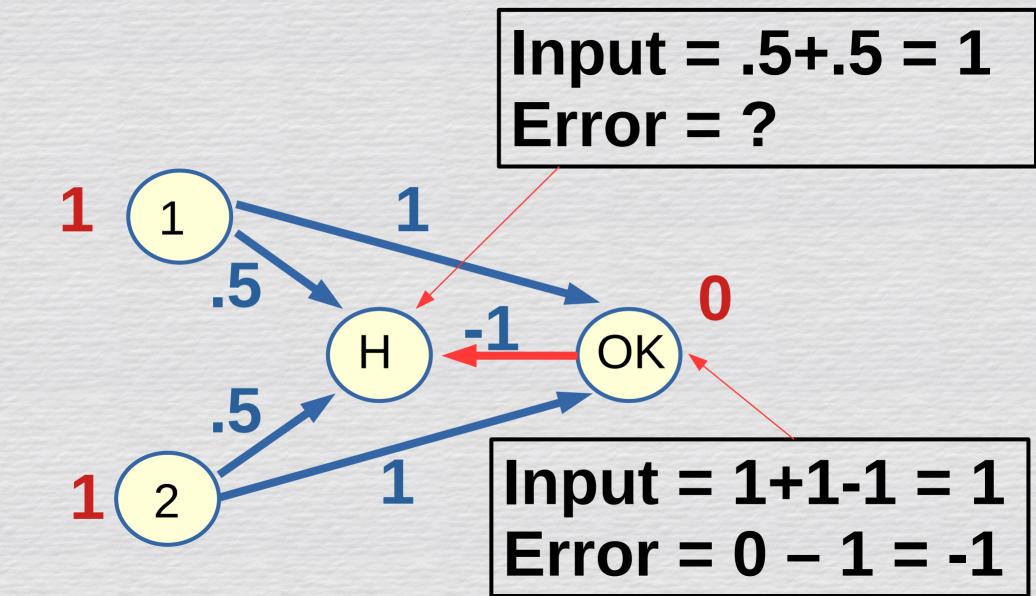
Student prediction

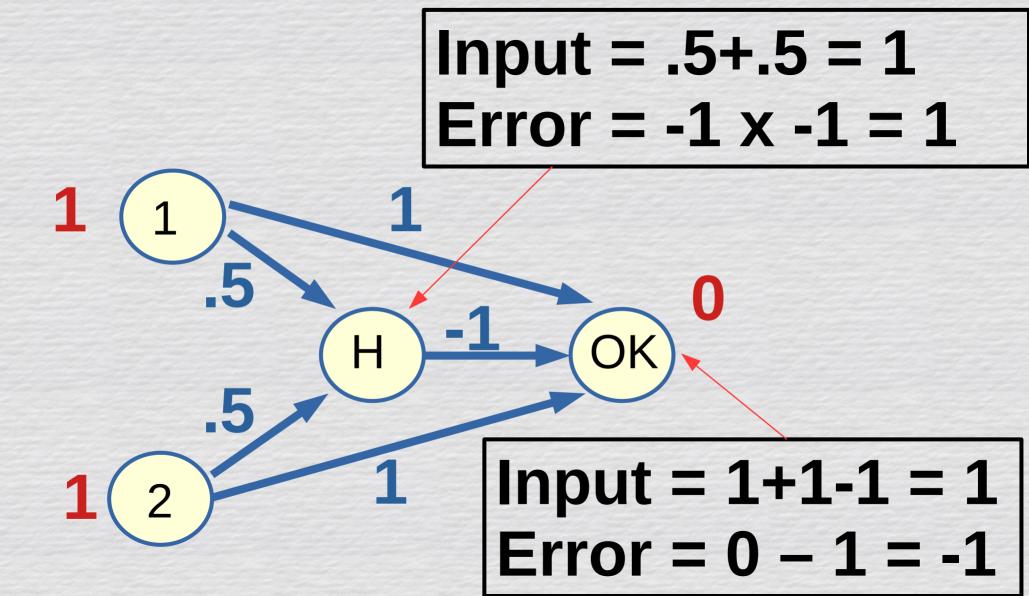
Defining error

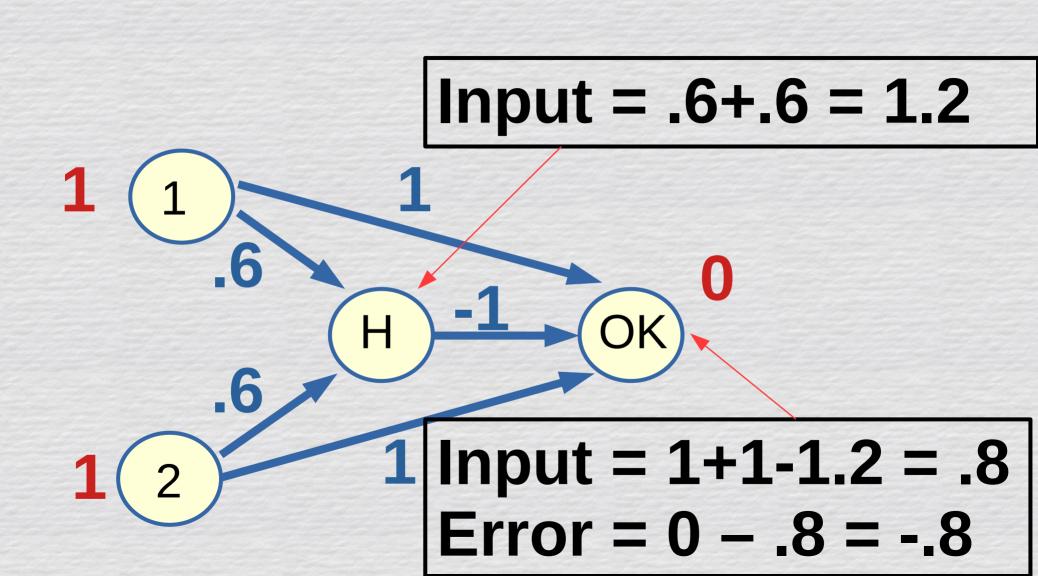
 $\Delta w_{13} = G(t - \Sigma aw)a_1$ Teacher Student prediction $E_3 = (t - \Sigma aw)$

 $\Delta w_{13} = G.E_{3.}a_{1}$



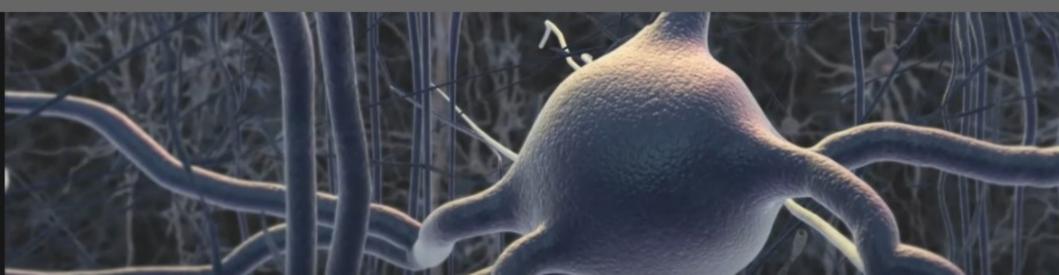








History of backprop



Standard story



Runelhart, Hinton & Williams (1986)

Invention of backprop



Kelley (1960)



Werbos (1974)

Invention of backprop

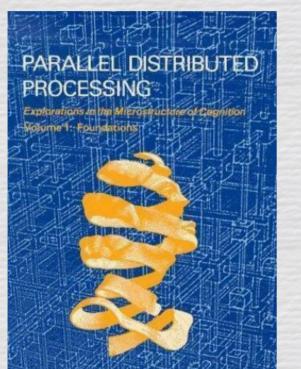


Yann LeCun

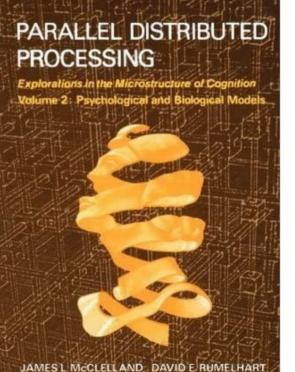


Sun-1 (1983) £24,000 in today's money

Connectionism



DAVID'E RUMELHART JAMES L MOCLELLAND, AND THE POP RESEARCH GROUP



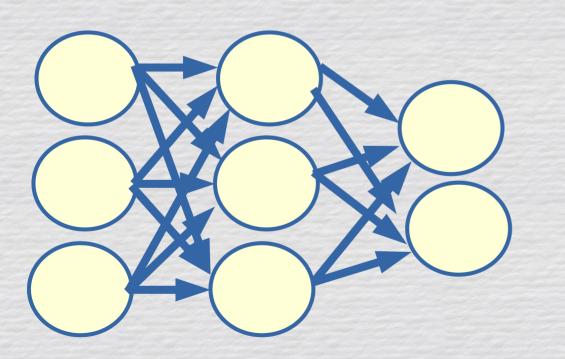
JAMES LIMCCLELLAND, DAVID E RUMELHART AND THE PDP RESEARCH GROUP



Power and limitations of backprop

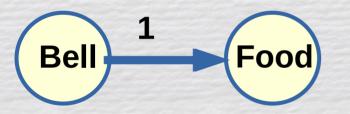


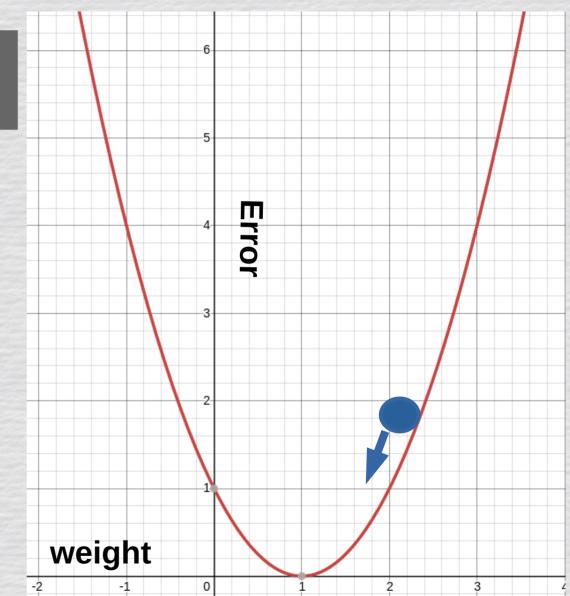
Universal approximators



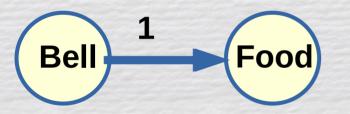
A multilayer feedforward network, with sufficient hidden units can represent any deterministic mapping between its inputs and its outputs - Hornik, Stinchcombe & White (1989)

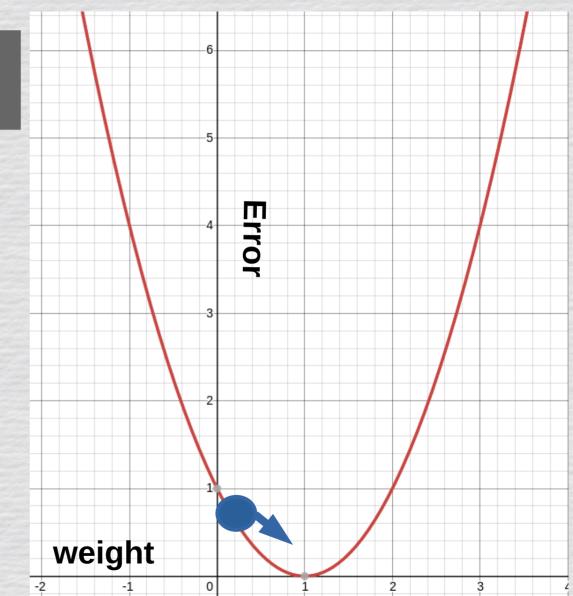
Error surface



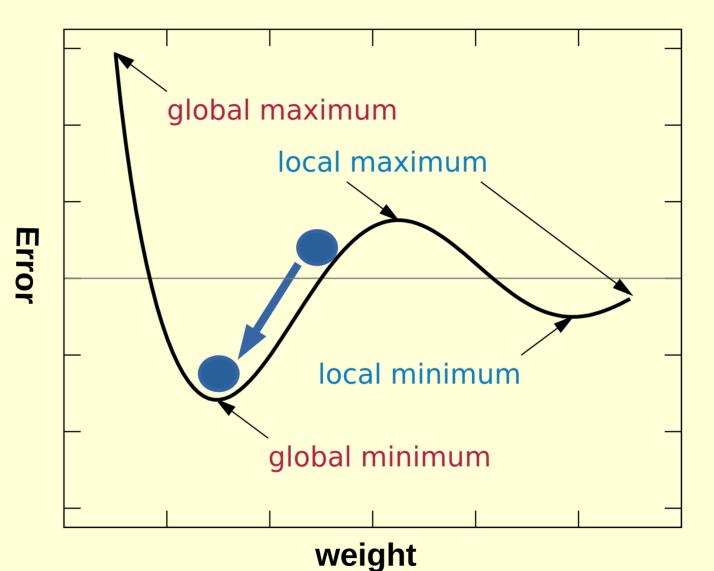


Error surface

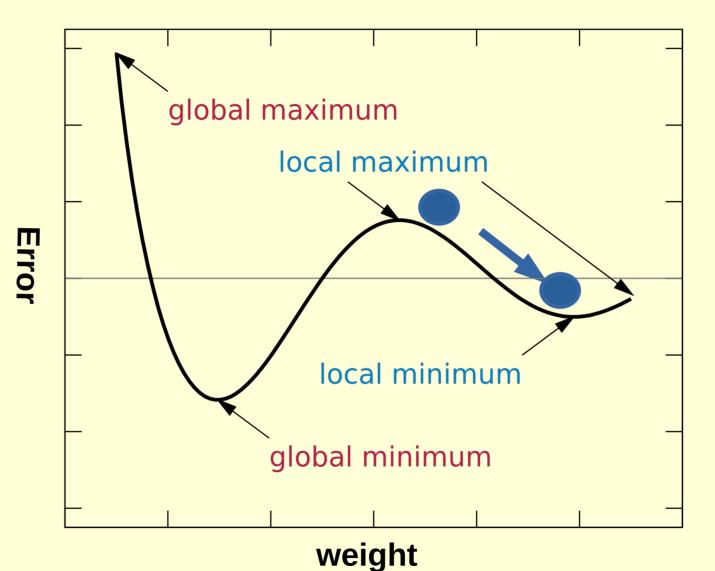




Error surface



Error surface



Interference

"Every time I learn something new, it pushes some old stuff out of my brain" - Homer Simpson

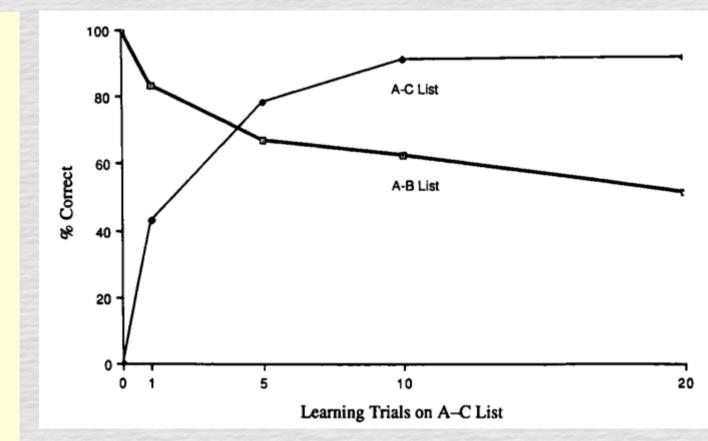


People: Retroactive Interference

Retroactive interference Barnes & Underwood (1959)

<u>List 1 (A-B)</u> dax – regal

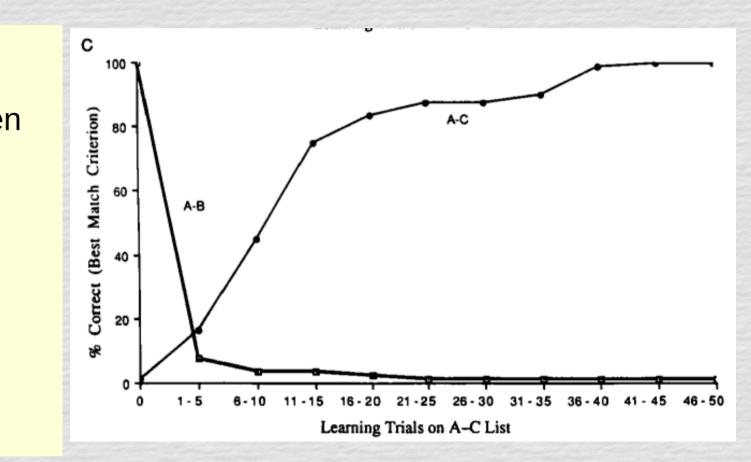
List 2 (A-C) dax – cabbage



. . .

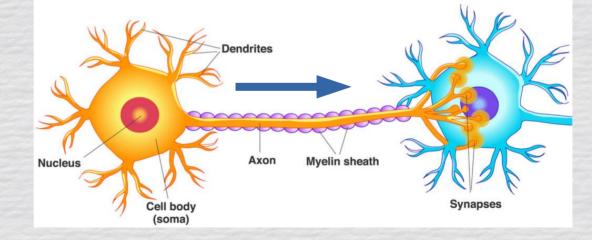
Backprop: Catastrophic Interference

Catastrophic interference McCloskey & Cohen (1989)List 1 (A-B) dax – regal . . . List 2 (A-C) dax – cabbage



Neural plausibility







Summary

